

# Midterm Presentation

## EML 4552C/EEL 4914C- Senior Design

Team # 19  
Jordan Berke  
Dustin McRae  
Khristofer Thomas  
Luis Bonilla  
Trevor Hubbard

### Google Mobile App for Compressor Performance (GE)

*Project Sponsor*  
General Electric



*Project Advisors:*

**Russell Wilburn**

*Industry Advisor, GE Oil & Gas*

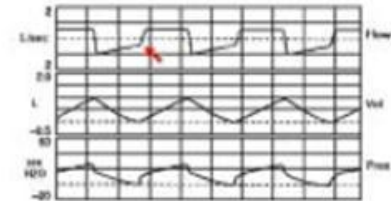
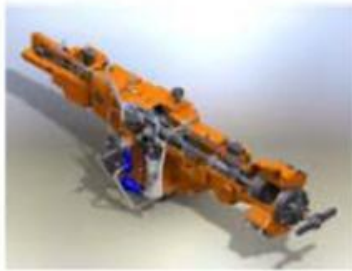
**Dr. Sam Taira**

*Department of Mechanical Engineering*

**Dr. Linda DeBrunner**

*Department of Electrical and Computer Engineering*

# Scope of the Project



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GE Title or job number  
9/1/2011

- Customer Needs

- Transfer data wirelessly to an Android phone.
- Assembly time less than 5 minutes.
- No modifications to pipes; non-intrusive method.
- Software must collect, store and display data.
- Working Demo.

# Sensor Update

- Utilized the DragonBoard to output signal to ultrasonic transducers
- Calls 16-bit up counter with resolution of 1.5 MHz
- Close enough to start testing
- Using basic low level functions for fast accurate signal reproduction

```
// Example 1a: Turn on every other segment on 7-seg display
#include <hidef.h> /* common defines and macros */
#include <mc9s12dg256.h> /* derivative information */
#pragma LINK_INFO DERIVATIVE "mc9s12dg256b"

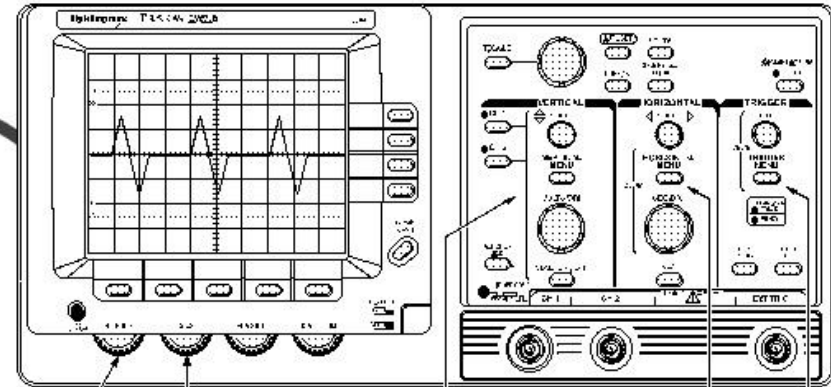
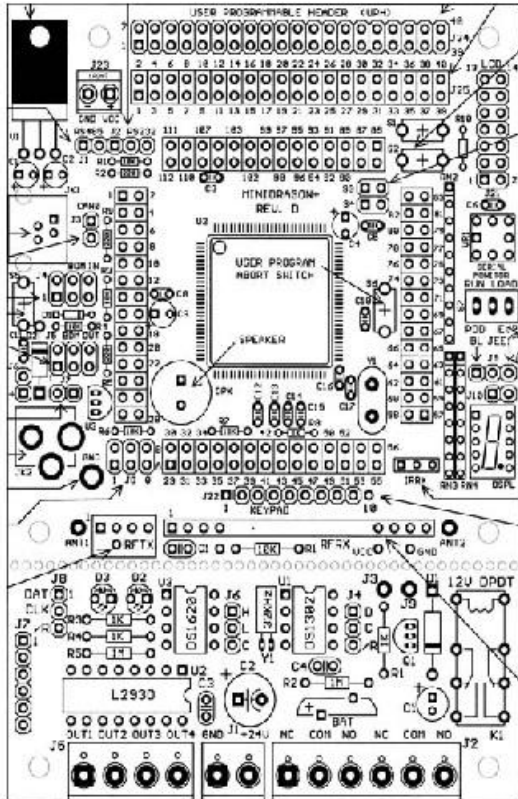
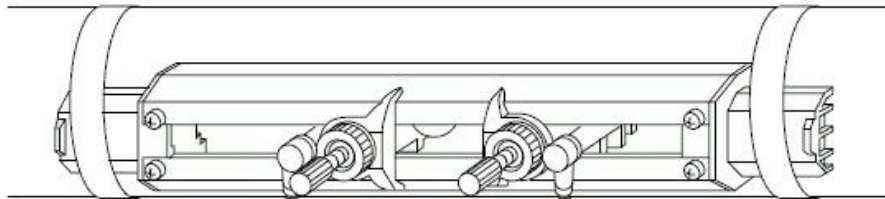
#include "main_asm.h" /* interface to the assembly module */

int period;
int pwidth;
int i=0;

void interrupt 14 handler(){
    i+=1;
    if(i==4){
        period=7238;
        i=0;
    }else period=10;
    ptrain6(period,pwidth);
}

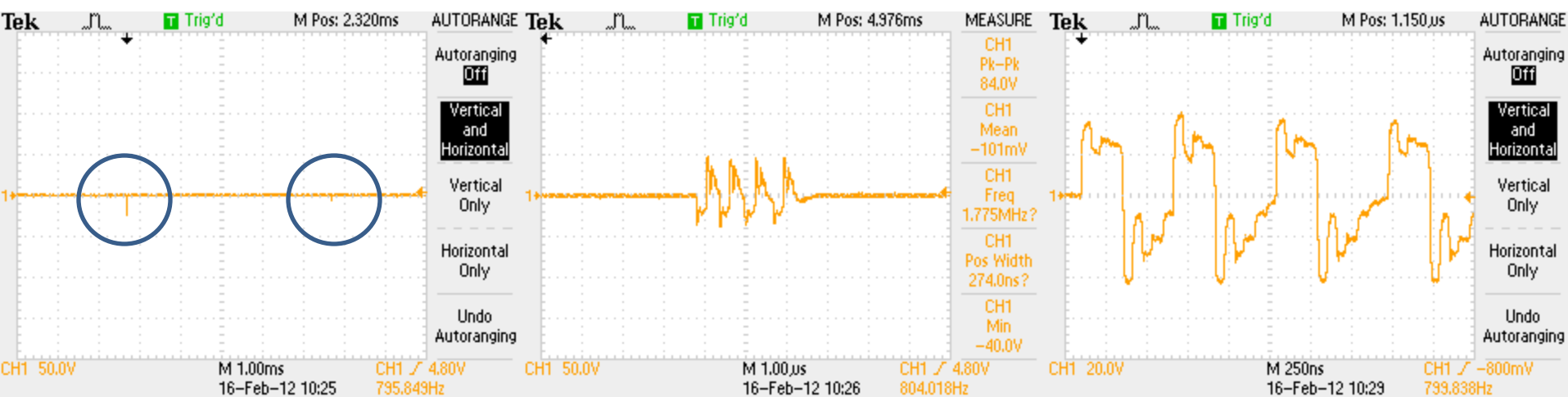
void main(void) {
    /* put your own code here */
    PLL_init(); /* set system clock frequency to 24 MHz
    ptrain6_init();
    period = 10;
    pwidth = 5;
    while(1){
    }
    for(;;) {} /* wait forever */
}
```

# Experimental Setup



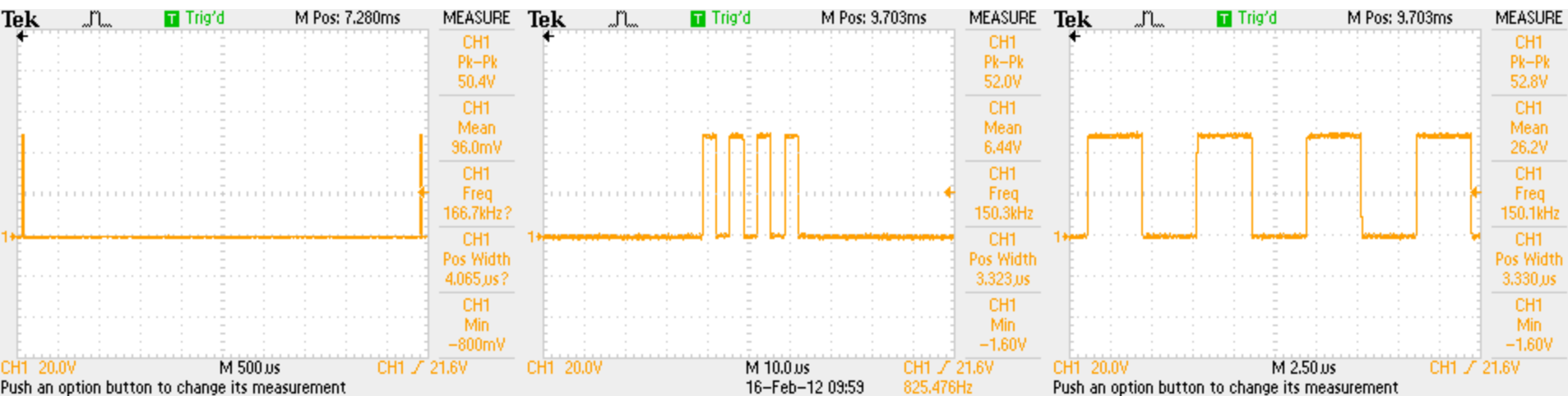
# Flow Meter Output

- Burst of four square waves with 250 ns period
- Multiple bursts located 500  $\mu$ s apart
- Approximately 50V peak to peak



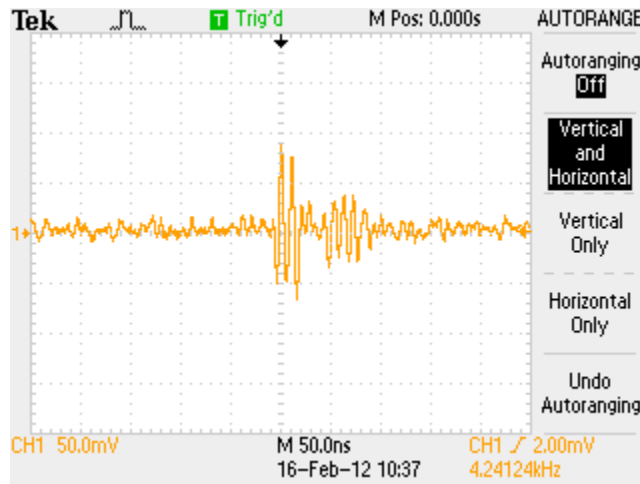
# DragonBoard Output

- Burst of four square waves with 2500 ns period (constraint of the TCNT)
- Multiple bursts located 500  $\mu$ s apart
- Approximately 50 V peak to peak

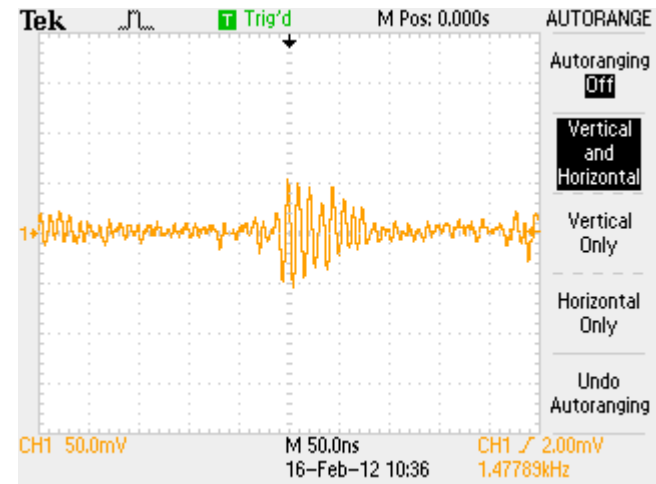


# Sensor Output

- Sensor output in air
- Proof of concept, real testing and refinement will be done on the test apparatus



Flow Meter Output



DragonBoard Output

# Wi-Fi on Single Board PC

- Original Wi-Fi USB adapter shipped from Technologic Systems did not support master mode with Linux driver, just Ad-Hoc.
- **Problem:** Most Android phones do not connect to Ad-Hoc networks with out rooting your phone.
- **Solution:** New Wi-Fi module ordered:



Penguin Wireless N USB Adapter for GNU/Linux



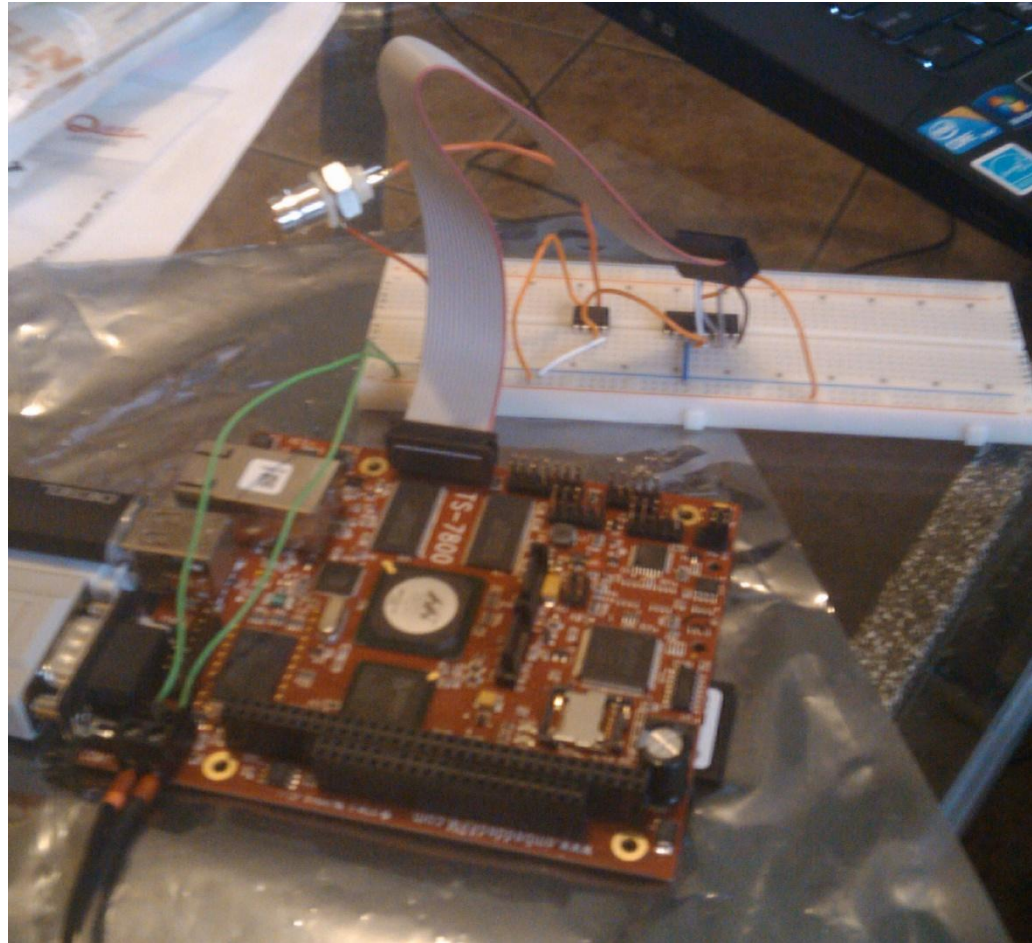
# Wi-Fi on Single Board PC

- **Problem:** Penguin adapter drivers require Linux kernel 2.6.37+. Technologic Systems only supports up to Linux kernel 2.6.34. (Most board components such as the SD Card are buggy on newer kernels)
- **Solution:** Cross compile own drivers with ARM architecture for 2.6.34.
- Drivers were compiled, but currently having trouble getting hostapd to work with firmware.
- Hostapd is what implements access point management in order to turn the Wi-Fi module into an access point.
- Matter of time. Cross compiling and transferring from Linux machine to SBC via SD Card is very time consuming.

```
#  
# Hardware crypto devices  
#  
# CONFIG_MV_CESA_TOOL is not set  
  
#  
# Library routines  
#  
CONFIG_BITREVERSE=y  
CONFIG_CRC_CCITT=m  
# CONFIG_CRC16 is not set  
CONFIG_CRC32=y  
CONFIG_LIBCRC32C=y  
CONFIG_ZLIB_INFLATE=m  
CONFIG_ZLIB_DEFLATE=m  
CONFIG_PLIST=y  
CONFIG_HAS_IOMEM=y  
CONFIG_HAS_IOPORT=y  
  
CONFIG_CFG80211=m  
CONFIG_LIB80211=m  
CONFIG_MAC80211=m
```

# Signal Generation From SBPC

- Preliminary circuit built.
- Not yet tested in lab.
- Still figuring out how to control Digital I/O from user space programs.



# Signal Generation From SBPC

- Operating System built on top of hardware => cannot access hardware directly.
- Memory mapped IO is used in order to access hardware from user space.
- Still figuring out how to control Digital I/O from user space programs.
- mmap() system call is used in order to achieve this.

```
#include<unistd.h>
#include<sys/mman.h>
#include<fcntl.h>
#include<stdio.h>
#include<stdlib.h>

#define DIOBASE 0xe8000008
#define CLK (1 << 5)
#define MOSI (1 << 3)
#define MISO (1 << 1)

#define RO *(dioptr + 0x05/sizeof(unsigned char))
#define RW *(dioptr + 0x09/sizeof(unsigned char))

volatile unsigned char *dioptr;

-void init_dio0 {
int fd;
fd = open("/dev/mem", O_RDWR|O_SYNC);
dioptr = (unsigned char *)mmap(0, getpagesize(),
PROT_READ|PROT_WRITE, MAP_SHARED, fd, DIOBASE);
RW |= CLK;
}

-unsigned char dio8(unsigned char c) {
int i;
unsigned char m0c0, m1c0, m0c1, m1c1;
unsigned char ret = 0;

m1c1 = RW | MOSI | CLK;
m1c0 = m1c1 & ~CLK;
m0c0 = m1c0 & ~MOSI;
m0c1 = m1c1 & ~MOSI;
- for(i=0; i < 8; i++) {
if (c & 0x80) {
RW = m1c1;
ret <<= 1;
RW = m1c0;
c <<= 1;
if (~RO & MISO) ret |= 1;
} else {
RW = m0c1;
ret <<= 1;
RW = m0c0;
c <<= 1;
if (~RO & MISO) ret |= 1;
}
}
RW = m0c1;
return ret;
}

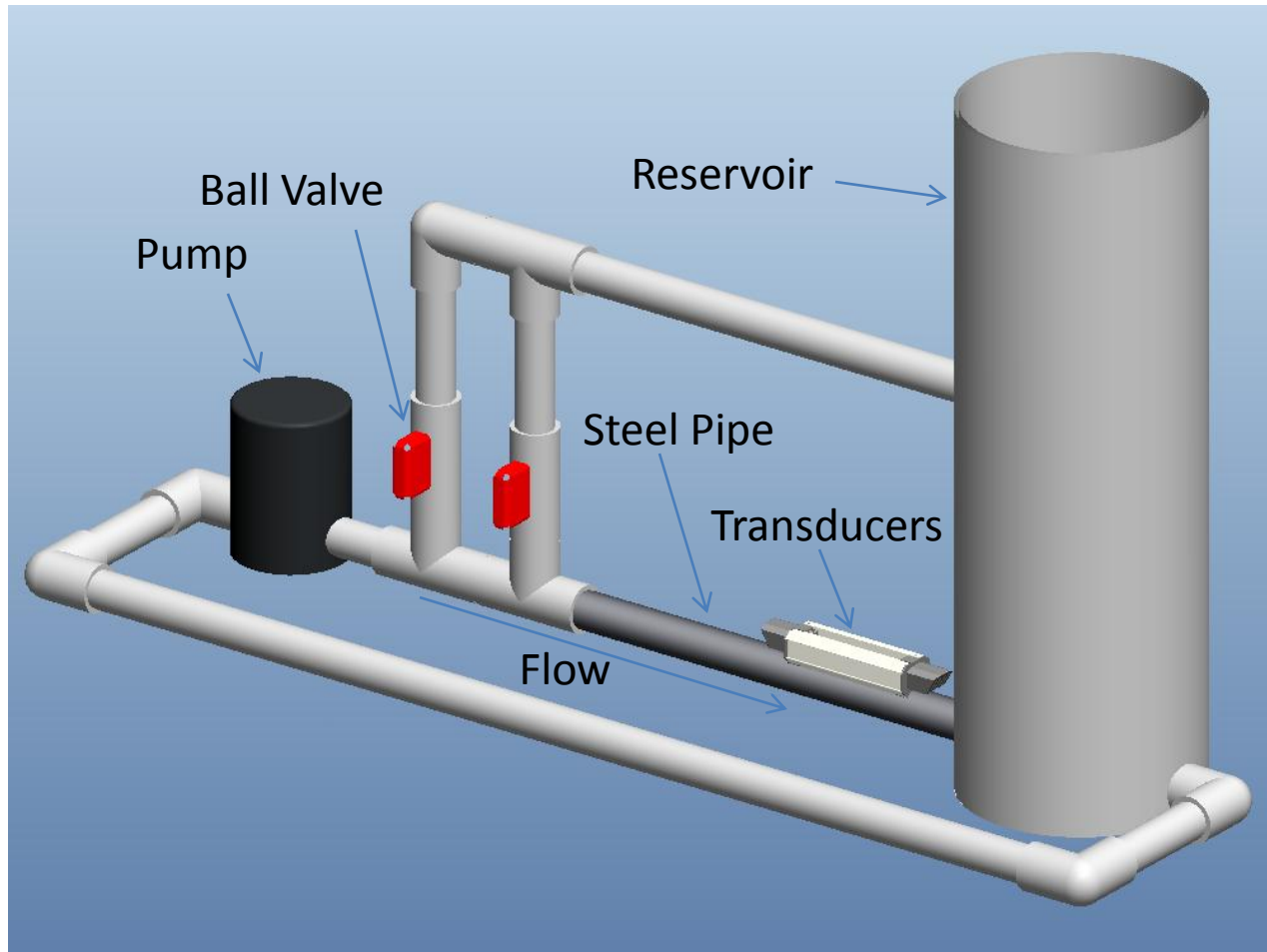
-unsigned int dio32(unsigned int c) {
int i;
unsigned char m0c0, m1c0, m0c1, m1c1;
unsigned int ret = 0;

m1c1 = RW | MOSI | CLK;
m1c0 = m1c1 & ~CLK;
```

# Flow Test Apparatus

- Need a test apparatus for development, calibration, and demonstration of instrumentation and phone app
  - Consistent conditions needed to develop the entire system
  - Ability to adjust flow will aid calibration process
- Our instrument ultimately needs to measure flow of natural gas (air)
- Main goal is to prove the concept
- We will start with a setup to measure water flow
  - Our transducers are tuned to operate at the higher frequency needed for liquids (due to higher speed of sound in liquid medium)

# Flow Test Apparatus



# Flow Test Apparatus

- Once concept is proven, we can attempt measurement in air
  - Speed of sound in air is lower (1117 ft/s, vs. 4814 ft/s for water)
  - May or may not require transducers that operate at lower frequency
  - Since SBPC can handle the higher frequencies needed for liquid measurements, it can easily handle any good frequency for air

# Mobile Application

- The velocity inside the compressor pipes are expected to fluctuate by some small amount but we are only interested in large fluctuations
- Need to make a running average algorithm for our incoming velocity data to normalize and eliminate small fluctuations in the data
- Derived formula for the average of all points thus far at any given point

$$Current_{avg} = \frac{(Prev_{avg} \times Prev_{total}) + new\ point}{Current_{total}}$$

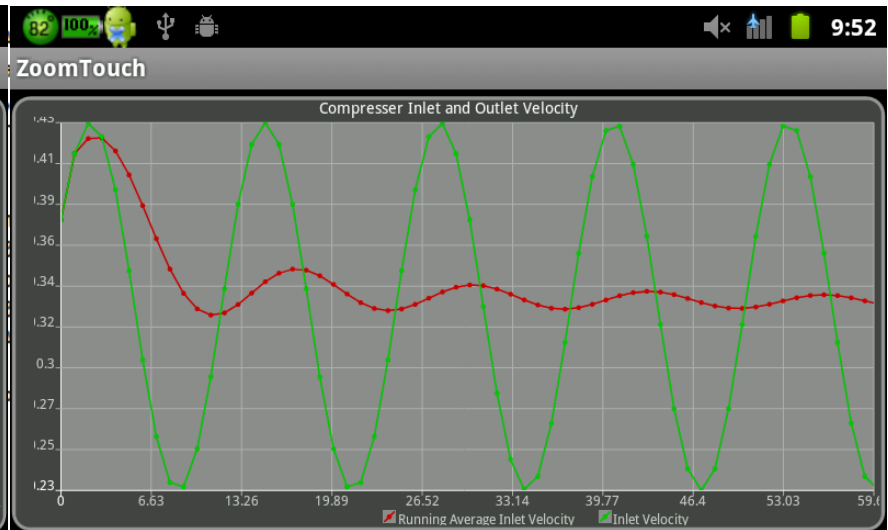
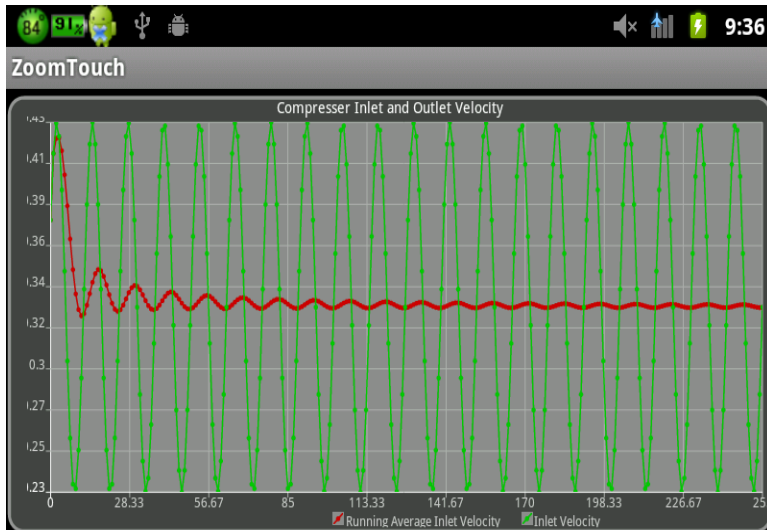
# Mobile Application

graphs.java

ZoomTouchActivity.java

```
final Vector<Double> inletAvg = new Vector<Double>();
inletAvg.add(inlet[0]);
final Vector<Double> inletVel = new Vector<Double>();
inletVel.add(inlet[0]);
final Vector<Double> outletAvg = new Vector<Double>();
outletAvg.add(inlet[0]);
final Vector<Double> outletVel = new Vector<Double>();
outletVel.add(inlet[0]);

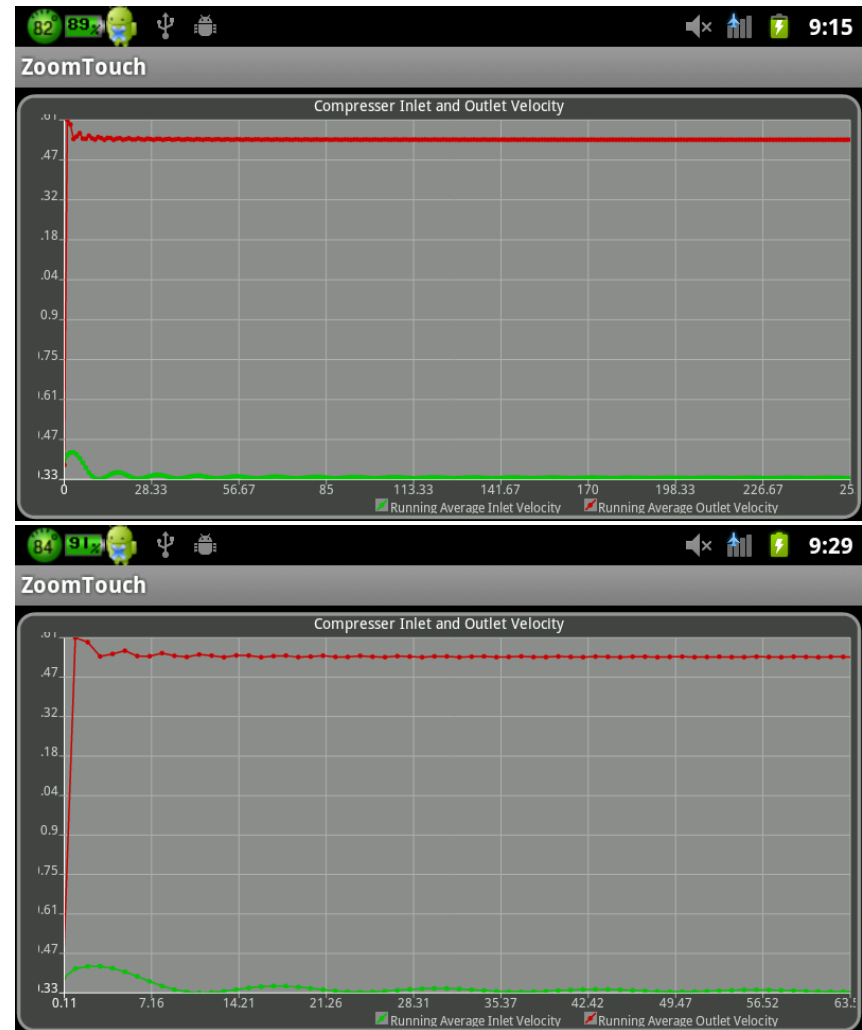
for (int element = 1; element < inlet.length; element++) {
    inletAvg.add((inletAvg.get(element-1)*(inletAvg.size()-1)+inlet[element])/inletAvg.size());
    inletVel.add(inlet[element]);
}
for (int element = 1; element < inlet.length; element++) {
    outletAvg.add((outletAvg.get(element-1)*(outletAvg.size()-1)+outlet[element])/outletAvg.size());
    outletVel.add(outlet[element]);
}
}
```





# Mobile Application

- Realistic Graph of what we expect our velocity measurements to look like
- Includes inlet and outlet velocities
- Graph also has built in zooming function which changes the x-axis
- Future work will include the y-axis (i.e. full zooming into a specific point)

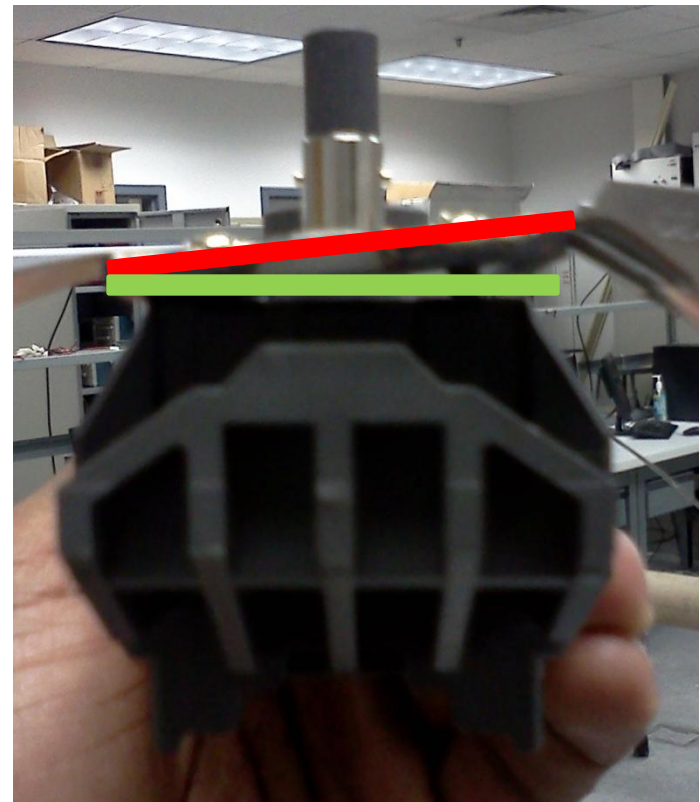


# Mobile Application

- Next steps: working on setting up laptop to send data to phone to use as testing tool
- Will use this to test reception of the data and proper storage into the database of phone
- Have been encountering difficulties with type mismatching while coding. Foresee issues with data type being stored in database and type needed for androidplot graphing functions.
- Might have to modify database to store in specific data type to simplify type-conversions during the calculation and graphing stages.

# Results from Testing the Mounting System

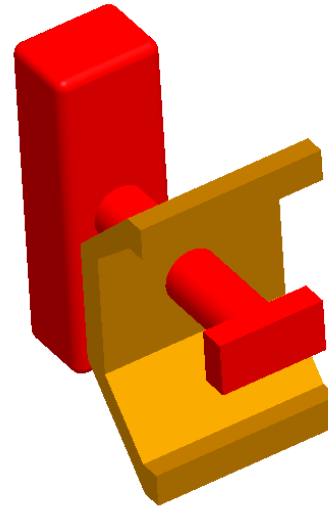
- Satisfied second customer need
- Discovered modifications needed for proper fitting Mounting System
- Developed procedures for easier mounting



Unlevel attachment

# Housing Unit Progress

- Method for attaching the housing unit has been selected
- Seen in figure 2, the design features four outer track grips with keys
- Dimensions for the housing unit are to be determined

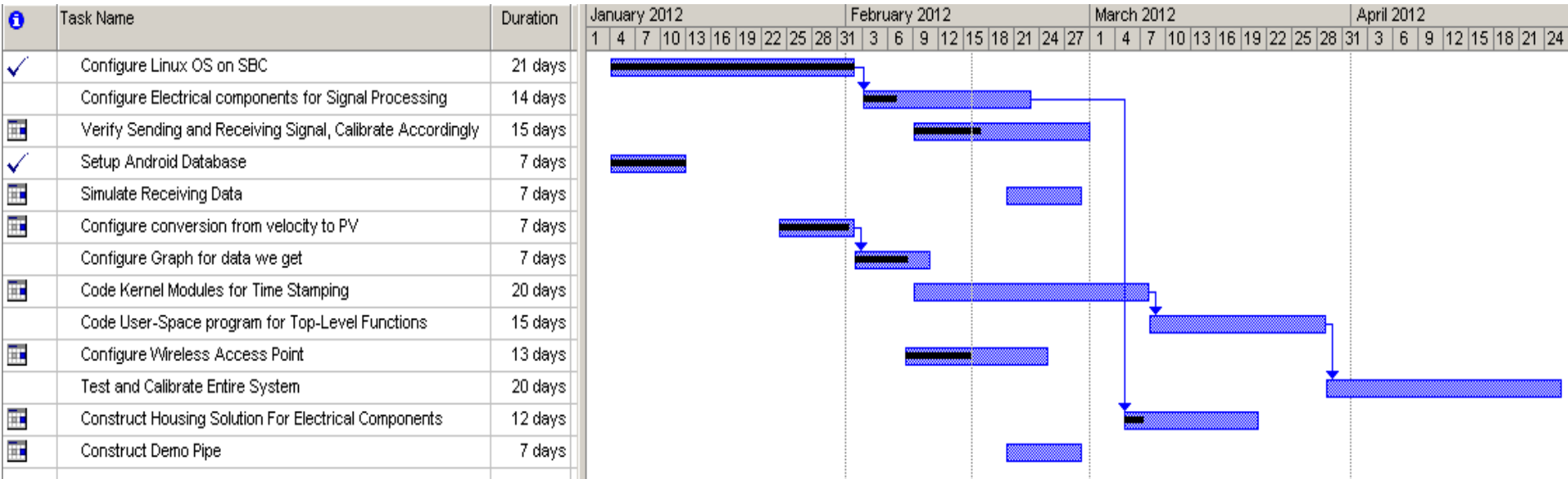


Outer Track Grips

Track of Transducers



# Project Plan



# Questions



Image Provided by: <http://www.datingadvice4christiansingles.com/image-files/askaquestion.jpg>